Mechanical Activation of the ShapeMemory Effect in Polymers for Biomedical Applications <u>Christopher M. Yakacki PhD^{1,2}</u>, Roxanne Likos³, Robert Lamell^{1,3}, Daniel Guigou^{1,4}, Ken Gall PhD^{1,2,4} ¹Research and Development, MedShape Solutions Inc, Atlanta, GA 30318 ²School of Materials Science and Engineering, The Georgia Institute of Technology, Atlanta, GA 30332 ³W. H. Coulter School of Biomedical Engineering, The Georgia Institute of Technology, Atlanta, GA 30332 ⁴George Woodruff School of Mechanical Engineering, The Georgia Institute of Technology, Atlanta, GA 30332

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Statement of Purpose: Shape-memory polymers (SMPs) are defined as a class of "smart" materials that are able to adapt and respond to a stimulus. SMPs can be activated via heat, light, alternating magnetic fields, and solvents; however, these techniques are mostly based on *thermal* activations.(I) M a n y r e s e a r c exploiting SMPs for biomedical applications.(I)

This study proposes a new method of mechanically -memory effect to allow for activating the shape temperature-independent a d nemar -instantaneous recovery. Shape -memory r e c o v e isy driven by entropy elasticity and relies on the temperature to reach a critical value to overcome intermolecular frictional forces. Rather than solely relying on temperature, mechanical energy can be a dded into the system to overco me these frictional forces and drive shape recovery. The purpose of this study was to investigate if mechanical forces could be used to activate SMP acrylate network with s res temperature and crosslinking density.

Methods: SMP networks were photo -polymerized from tert-butyl acrylate (tBA) and poly(ethylene glycol) dimethacrylate (PEGDMA). The molecular weight of crosslinker (PEGDMA) was controlled such that networks with 10, 20, and 40wt% crosslinking maintained a glass transition temperature (T g) of ~50°C. Cylindrical -tube samples were machined from polymerized rod stock and programmed for shape -memory above T g u s i n g a three piece sabot (Figure 1). This process axially strained the samples 26%. A second set of samples was machined to the same dimensions of the programmed SMP samples. Both sets of samples were compressed at 0.1mm/s to deform the samples to the original shape of the programmed SMP samples at 20, 27, 34, and 41°C.



Figure 1: Process for programming shape-memory effect. Lastly, SMP bone plugs were tested in a mock tenodesis setup. The SMP plugs were activated to fixate a nylon tendon in a synthetic bone hole. Samples were activated either by compression (mechanical) or temperature (thermal) and tested for fixation strength over time. **Results:** Samples programmed with shape -memory showed a substantial drop in modulus, strength, and energy required to deform to samples compared to identical shaped samples not programmed for shape memory at corresponding t emperatures. Figure 2 compares the response for the 10wt% crosslinked samples, which is representative of the remaining networks. On average, the SMP samples showed a 50 - 70% reduction in energy required for deformation compared to non-SMP group, which is summarized for all the networks and temperatures in Figure 3.

In the tenodesis model, mechanically activated SMP samples initially held 25% of fipation compared tos10@N d of fixation by thermally activated samples. After 30 minutes, the mechanically activ ated samples showed a slight drop in fixation strength to 200N, while thermally activated samples increased to 155N.



Figure 2: Stress-strain behavior of samples programmed as a SMP compared to identically machined samples not programmed with shape-memory (non-SMP).





Conclusions: T h e s e r e s u l t s s h o w forces/energy can be used to supplement thermal energy to activate the shape -memory effect. Furthermore, the force required to activate strain recovery is substantially less than identical samples not programmed for shape memeory.

References:

1. C. Yakacki, K. Gall, in *Advances in Polymer Science*. 2010; vol. Shape Memory Polymers: 147-175.